# **Gu-Cheol Jeong**

Mobile (+1)689-808-7783 APT 317, 2401 Aldrich Street E-mail goochul@utexas.edu Austin, TX 78723

Website <a href="https://goochul.github.io/website/">https://goochul.github.io/website/</a>

LinkedIn <a href="https://www.linkedin.com/in/gcjeong91/">https://www.linkedin.com/in/gcjeong91/</a>

## RESEARCH INTERESTS

Robot Hardware Design & Control • Collision Robust Robot Manipulator • System Dynamics Design • CAD Design to Simulation • Sim2Real

## **EDUCATION**

The University of Texas at Austin

Austin, TX

Ph.D. Candidate in Mechanical Engineering

Aug 2019 – Present

Advisor: Dr. Ashish D. Deshpande

**Kookmin University** 

Seoul, South Korea

**Bachelor of Science in Mechanical System Engineering** 

Mar 2010 - Aug 2016

## PROFESSIONAL APPOINTMENTS

Graduate Research Assistant, National Science Foundation (NSF)

Aug 2023 – Present

Principal Investigator: Dr. Lei Zhou and Dr. Ashish D. Deshpande

Next-Generation Safe and Dexterous Robot Hands using High-Torque Direct-Drive Actuation

• Project Goal: Create and demonstrate a new type of robot hand with excellent manipulation dexterity and contact safety without sacrificing strength and hardware simplicity

Graduate Research Assistant, Sony Research Award Program

Aug 2022 - Aug 2023

Principal Investigator: Dr. Lei Zhou and Dr. Ashish D. Deshpande

High-torque Transparent Actuators For Next-Generation Interactive Robotic Hands

• Project Goal: Develop the robotic hands with high strength, and safety, dexterity using the new actuator.

**Research Scientist,** Korea Institute of Science and Technology (KIST)

May 2017 – Aug 2019

Principal Investigator: Dr. Keehoon Kim

Seoul, South Korea

• Designed and Controlled Powered prosthesis / Powered Exoskeleton / Haptic Interface

Undergraduate Research Assistant, Kookmin University

Jul 2015 – Aug 2016

Principal Investigator: Prof. Baek-Kyu Cho

Seoul, South Korea

• Analyzed, Designed and Controlled Biomimetic Hopping Leg Robot based on MIT Junior Cheetah

#### TECHNICAL SKILLS

- Engineering Software: Python · C · MATLAB · R · LabVIEW · SOLIDWORKS
- Dynamic Simulation: MuJoCo · Simscape

# **Gu-Cheol Jeong**

#### PROFESSIONAL SERVICE

### **Peer-Reviewed Article for:**

- IEEE Robotics and Automation Letters (RA-L)
- IEEE International Conference on Intelligent Robots and Systems (IROS)
- IEEE International Conference on Robotics and Automation (ICRA)

## **High School Research Academy (Summer 2024 – UT Austin):**

Hardware Design Instructor

• Taught 30 high school students to assemble six BaRiFlex robotic hands; and guided them in collecting manipulation-task data for imitation learning;

### TEACHING ACTIVITIES

## The University of Texas at Austin, Austin, TX

# Graduate Teaching Assistant, Department of Mechanical Engineering

•	ME366J	Mechanical Engineering Design Methodology	Fall 2019
•	ME318M	Programming & Engineering Computational Methods	Spring 2020
•	ME380R	Robot Mechanism Design	Spring 2022

#### PEER REVIEWED ARTICLES

## **Journal Publication**

[J2] <u>Gu-Cheol Jeong</u>, Stefano Dalla Gasperina, Ashish D. Deshpande, Lillian Chin and Roberto Martin-Martin, "BiFlex: A Passive Bimodal Stiffness Flexible Wrist for Manipulation in Unstructured Environments", Under Review in Robotics and Automation Letters, <a href="https://robin-lab.cs.utexas.edu/BiFlex/">https://robin-lab.cs.utexas.edu/BiFlex/</a>

[J1] Man Bok Hong, Sin Jung Kim, Yong Seok Ihn, <u>Gu-Cheol Jeong</u>, and Keehoon Kim, "*KULEX-Hand: An Underactuated Wearable Hand for Grasping Power Assistance*," IEEE Trans. Robot. 35, 420 –432 (2019)

## **Conference Proceedings**

[C3] <u>Gu-Cheol Jeong</u>, Arpit Bahety, Gabriel Pedraza, Ashish D. Deshpande, and Roberto Martin-Martin, "BaRiFlex: A Robotic Gripper with Versatility and Collision Robustness for Robot Learning", In 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2024, **Best Robot Mechanisms and Design paper**, https://robin-lab.cs.utexas.edu/bariflex

[C2] <u>Gu-Cheol Jeong</u>, Yeoeun Kim, Wooseong Choi, Hyun-Joo Lee, Sang Rok Oh, and Keehoon Kim, "On the Design of a Novel Underactuated Robotic Finger Prosthesis for Partial Hand Amputation", 2019 IEEE International Consortium for Rehabilitation Robotics 2019

[C1] <u>Gu-Cheol Jeong</u>, Kwon Joong Son, and Keehoon Kim, "Miniaturization of Ultrasonic Variable-Friction Tactile Display", Korea Robotics Society Annual Conference (KRoC 2018)

# Gu-Cheol Jeong

### HONORS AND AWARDS

'Sung-Gok' Academic Scholarship

• Foreign Language Academy Achievement Scholarship

Exchange Program Scholarship Fall 2014 & Spring 2015

## **EXTRA EXPERIENCE**

## **Korea Army Training Center**

Aug.2011 - May.2013

Fall 2015

Spring 2016

Sergeant, Military Trainer

Chungcheongnam-do, South Korea

 Managed the training of 13 recruits and subsequently earned a promotion to manager within a 200-member company.

## 'Journey To Get Happy' Volunteer Program

May. 2013 - Jul. 2015

Volunteer

Gunpo-si, Korea

- Funded by City of Gunpo, Sponsored by Gunpo Youth Center, in collaboration with Nepal
- Participated in a community-engaged program between Gunpo Youth Center and Nepal Smile Orphanage, where volunteers and students raised funds to send 100kg of stationary to support Smile Orphanage.

## 'Donghaeng' Teaching Volunteer Program

Sept.2013 - Jul.2014

Math Teacher

Seoul, Korea

Taught underprivileged high school students every week for one semester

**Exchange Student** 

Jul.2014 – Jul.2015

Student Representative from Kookmin University

Nevada, United States

• Promoted Korean culture at the University of Nevada, Reno

#### COLLABORATORS / REFERENCES

- **Prof. Ashish D. Deshpande**: Professor, UT Austin [contact]
- Prof. Roberto Martin-Martin: Assistant Professor, UT Austin [contact]
- **Prof. Lei Zhou:** Assistant Professor, UW-Madison [contact]
- **Prof. Lillian Chin:** Assistant Professor, UT Austin [contact]
- **Prof. Ben Abbatematteo:** Assistant Professor, UT Austin [contact]
- **Prof. Keehoon Kim:** Associate Professor, POSTECH [contact]
- Stefano Dalla Gasperina: Postdoctoral Researcher, UT Austin [contact]